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# Interaction of Void Spacing and Material Size Effect on Inter-Void Flow Localization

The ductile fracture process in porous metals due to growth and coalescence of micron scale voids is affected not only by the imposed stress state but also by the distribution of the voids and the material size effect. The objective of this study is to understand the interaction of the inter-void spacing (or ligaments) and the resultant gradient-induced material size effect on void coalescence for a range of imposed stress states. To this end, three-dimensional finite element calculations of unit cell models with a discrete void embedded in a strain gradient-enhanced material matrix are performed. The calculations are carried out for a range of initial inter-void ligament sizes and imposed stress states characterized by fixed values of the stress triaxiality and the Lode parameter. Our results show that in the absence of strain gradient effects on the material response, decreasing the inter-void ligament size results in an increase in the propensity for void coalescence. However, in a strain gradient-enhanced material matrix, the strain gradients harden the material in the inter-void ligament and decrease the effect of inter-void ligament size on the propensity for void coalescence. [DOI: 10.1115/1.4049022]

Keywords: micromechanics, plasticity

### 1 Introduction

In porous metals, void coalescence often drives the onset of the macroscopic flow localization that marks the end of uniform deformation and acts as a precursor to failure, as well as the initiation and propagation of ductile cracks [1–3]. Previous studies suggest that for conventional plasticity theory, where no material length scale enters the constitutive law (the absence of stress/strain gradient-induced size effect), a decrease in the inter-void spacing promotes void coalescence [4,5] and results in the collapse of the vield surface [6,7]. While for a fixed inter-void spacing, it is well established that the imposed stress state has a pronounced effect on the onset of void coalescence in the conventional plasticity theory. For example, it has been shown that an increase in the imposed stress triaxiality (a ratio of the first to second stress invariant) promotes void growth and early onset of void coalescence [8-11]. Void coalescence is simply the event where the plastic flow localizes within the inter-void ligaments and successively links the neighboring voids [9]. The plastic flow localization within the inter-void ligament, however, will induce plastic strain gradients that in turn may affect the strengthening and hardening of the material. This raises a fundamental question: how does the interaction of inter-void spacing (or ligament size) and the gradient-induced material size effect affect the localization of plastic flow causing void coalescence for a given stress state?

The gradient-induced size effect resulting in strengthening and hardening in metals has been confirmed in many material tests involving nonuniform deformation including indentation [12,13], torsion [14], and bending [15]. The size-dependent material response on the micron scale in metal plasticity implies that the

growth of micron-sized voids also exhibits significant size effects [16,17]. In general, it has been shown that the gradient-induced size effect leads to slower growth rates for smaller voids [18-22]. An accurate representation of void coalescence due to plastic flow localization within micron-sized inter-void ligaments, therefore, also requires material models that represent stresses over the relevant length scales. Phenomenological theories describing the strengthening and hardening due to plastic strain gradients express the plastic work in terms of both plastic strain and plastic strain gradient, thereby introducing a length scale into the material model. Herein, the strain gradient plasticity theory proposed by Gudmundson [23] is used, which includes both dissipative (nonrecoverable) and energetic (recoverable) gradient contributions within a small strain formulation based on viscoplasticity. The mathematical formulation and associated variational structure originate from Fleck and Willis [24], and the material model is implemented into the commercial finite element software ABAQUS using a user element (UEL) subroutine [25].

The objective of this study is to understand the interaction of the inter-void spacing (or ligament size) and the resultant gradient-induced material size effect on void coalescence for a range of imposed stress states. To achieve this, three-dimensional finite element unit cell calculations for a periodic array of initially spherical voids embedded in a strain gradient-enhanced material matrix are carried out. Several unit cell geometries have been analyzed to investigate the effect of inter-void ligament size under multiple loading conditions. The imposed stress states are characterized by fixed values of the stress triaxiality and the Lode parameter (a measure of the third stress invariant). The value of the Lode parameter is shown to affect the evolution of voids in computations involving conventional plasticity theory [5,26–29] and in experiments [30–32] only at relatively low stress triaxiality levels. However, it is likely that in an anisotropic material matrix [33]

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with anisotropy introduced by the void distribution [5], as for the present investigation, the effect of the Lode parameter can be important even at high stress triaxialities.

Our results show that for a conventional material matrix, increasing the inter-void ligament size results in an increase in the critical stress to void coalescence, up to a threshold value of inter-void ligament size. The sensitivity of the critical stress to the inter-void ligament size is found to increase with the increasing stress triaxiality. The quantitative effect of the Lode parameter is found to be small for the stress triaxiality values varying from 1 to 3. However, for inter-void ligament sizes below the threshold value, the critical stress is smallest for a Lode parameter value of -1, whereas above the threshold value, the critical stress is smallest for a Lode parameter value of 0. For a void in a strain gradient-enhanced material matrix, the value of the critical stress for void coalescence increases with the increasing length parameter, i.e., increasing gradient effect. This effect of the length parameter on the critical stress magnitude is found to increase with increasing imposed stress triaxiality and decreasing inter-void ligament size. This is because at higher stress triaxiality values and for smaller inter-void ligament sizes, there is an increase in the propensity for plastic flow localization that introduces strong plastic strain gradients and in turn hardens the ligament. This mechanism leads to a decrease in the dependence of critical stress on the inter-void ligament size with the increasing length parameter. The gradient-induced strengthening also tends to homogenize the deformation in the unit cell, thus decreasing the effect of the Lode parameter.

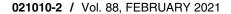
The structure of this article is as follows. Section 2 frames the study and presents the numerical method. The unit cell geometries considered, the method utilized to impose proportional loading throughout the deformation history, and the strain gradient plasticity material model are presented in Sec. 2. The numerical results are presented and discussed in Sec. 3. Finally, the key results and conclusions of this study are summarized in Sec. 4.

#### **2** Problem Formulation and Modeling Approach

This work considers a limit load-type analysis to determine the critical stress level at which a given microstructure configuration loses load-carrying capacity. Hence, an elastic-perfectly plastic material model is employed. The configuration of the unit cell and the simulation setup is described in Sec. 2.1, while the approach to prescribe a constant value of stress triaxiality and Lode parameter is outlined in Sec. 2.2.

**2.1 Unit Cell Geometry and Finite Element Mesh.** Threedimensional finite element calculations are carried out to model the response of an array of spherical voids with initial radius  $r_0$ , Fig. 1. The unit cell has edge lengths  $2a_i^0$  along the three coordinate axes,  $x_i$  (i=1, 2, 3), and inter-void spacings thereby equal  $2l_i^0 = 2a_i^0 - 2r_0$ . Symmetry about three planes perpendicular to the coordinate axes implies that only 1/8 of the unit cell needs to be modeled.

For all unit cells considered, the initial void volume fraction is  $f_0 = 0.01$ , where  $f_0 = (4/3\pi r_0^3)/(8a_1^0 a_2^0 a_3^0)$ . The initial void radius,  $r_0$ , is kept constant, while the cell dimensions are varied to achieve various initial inter-void spacings as given in Ref. [5]. The geometric parameters for the different cell dimensions are given in Table 1. For all unit cells,  $a_1^0/r_0 = a_2^0/r_0$ . Finite element meshes for four unit cell configurations are shown in Fig. 2. The modelling setup does not account for softening due to void evolution since a small strain formulation is used. It is assumed that the unit cell represents the material condition immediately before failure, neglecting the deformation history leading to this state. Hence, model predictions for the loss of load-carrying capacity signal the onset of localization. The critical equivalent stress at the onset of localization is recorded and reported in Sec. 4.



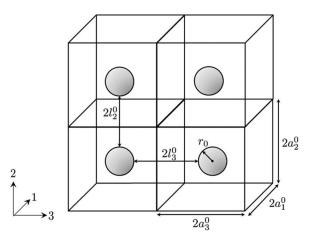


Fig. 1 Schematic showing the periodic arrangement of voids in the  $x_2$  and  $x_3$  plane. The distribution along the  $x_1$  direction is not shown for simplicity.

Table 1 Geometric parameters for the various unit cells considered for  $f_0 = 0.01$ 

$a_1^0/r_0 = a_2^0/r_0$	$a_3^0/r_0$	$l_1^0/r_0 = l_2^0/r_0$	$l_{3}^{0}/r_{0}$
6.06	1.43	5.05	0.43
5.55	1.70	4.55	0.70
5.21	1.94	4.21	0.95
4.97	2.12	3.97	1.12
4.58	2.50	3.58	1.50
4.18	3.00	3.18	2.00
3.75	3.75	2.75	2.75

Note: Based on Ref. [5].

**2.2** Numerical Method. The unit cells are subject to prescribed displacements, and the boundary conditions applied to the faces of the cell are as follows:

$$u_1(a_1^0, x_2, x_3) = U_1(t), \quad T_2(a_1^0, x_2, x_3) = T_3(a_1^0, x_2, x_3) = 0$$
  

$$u_2(x_1, a_2^0, x_3) = U_2(t), \quad T_1(x_1, a_2^0, x_3) = T_3(x_1, a_2^0, x_3) = 0 \quad (1)$$
  

$$u_3(x_1, x_2, a_3^0) = U_3(t), \quad T_1(x_1, x_2, a_3^0) = T_2(x_1, x_2, a_3^0) = 0$$

The applied symmetry boundary conditions are as follows:

$$u_1(0, x_2, x_3) = 0, \quad T_2(0, x_2, x_3) = T_3(0, x_2, x_3) = 0$$
  

$$u_2(x_1, 0, x_3) = 0, \quad T_1(x_1, 0, x_3) = T_3(x_1, 0, x_3) = 0$$
  

$$u_3(x_1, x_2, 0) = 0, \quad T_1(x_1, x_2, 0) = T_2(x_1, x_2, 0) = 0$$
(2)

In Eq. (1),  $U_1(t)$  is prescribed, and the time history of the displacements  $U_2(t)$  and  $U_3(t)$  are determined, such that a prescribed stress state is maintained. The loading direction is fixed in stress space by enforcing constant ratios between the normal stress components throughout the deformation history such that

$$\Sigma_{22} = \rho_2 \Sigma_{11}, \quad \Sigma_{33} = \rho_3 \Sigma_{11}$$
 (3)

where  $\rho_2$  and  $\rho_3$  are constants. The overall stress components  $\Sigma_{ij}$  are found by volume averaging over all elements, such that  $\Sigma_{ij} = \int_V \sigma_{ij} dV/V$ , where *V* is the unit cell volume.

The overall effective stress,  $\Sigma_e$ , and the overall hydrostatic stress,  $\Sigma_h$ , are given by

$$\begin{split} \Sigma_e &= \frac{1}{\sqrt{2}} \sqrt{(\Sigma_{11} - \Sigma_{22})^2 + (\Sigma_{22} - \Sigma_{33})^2 + (\Sigma_{33} - \Sigma_{11})^2} \\ \Sigma_h &= \frac{1}{3} (\Sigma_{11} + \Sigma_{22} + \Sigma_{33}) \end{split}$$

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which in terms of the relative stress ratios become

$$\begin{split} \Sigma_e &= \Sigma_{11} \frac{1}{\sqrt{2}} \sqrt{(1-\rho_2)^2 + (\rho_2-\rho_3)^2 + (\rho_3-1)^2} \\ \Sigma_h &= \Sigma_{11} \frac{1}{3} (1+\rho_2+\rho_3) \end{split}$$

The stress triaxiality, T, and the Lode parameter, L, are given by

$$T = \frac{\Sigma_h}{\Sigma_e} = \frac{\sqrt{2}}{3} \frac{1 + \rho_2 + \rho_3}{\sqrt{(1 - \rho_2)^2 + (\rho_2 - \rho_3)^2 + (\rho_3 - 1)^2}}$$
(4)

and

$$L = \frac{2\Sigma_{22} - \Sigma_{11} - \Sigma_{33}}{\Sigma_{11} - \Sigma_{33}} = \frac{2\rho_2 - 1 - \rho_3}{1 - \rho_3}$$
(5)

The overall effective strain,  $\overline{E}_e$ , is given by

$$\overline{E}_e = \frac{\sqrt{2}}{3}\sqrt{(E_{11} - E_{22})^2 + (E_{22} - E_{33})^2 + (E_{33} - E_{11})^2}$$
(6)

where the strain components,  $E_{ij}$ , are found in a way analogous to the stress components.

2.2.1 Multiple Point Constraints. The macroscopic normal stress components vary throughout the deformation, but the stress ratios are maintained in each increment of the simulation according to Eq. (3). This is achieved by creating multi point constraints through the user subroutine MPC in ABAQUS, which enables enforcing relationships between degrees-of-freedom in one or more nodes.

Additional degrees-of-freedom are added to impose boundary conditions on all sides of the model while prescribing the stress ratios. Three dummy nodes,  $N_i$ , are created outside of the mesh and connected to one connector node, M, in the mesh as shown in Fig. 3. This connection is made through spring elements (SPRING2 elements from the ABAQUS element library). The

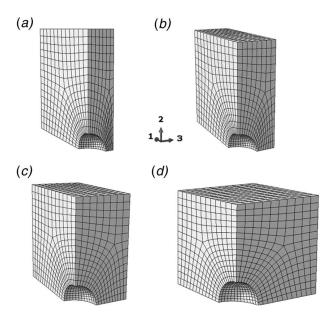


Fig. 2 Finite element meshes showing 1/8 of the unit cell with an initially spherical void of radius  $r_0$  in the center giving an initial void volume fraction of  $f_0 = 0.01$  for (a)  $\frac{l_1^0}{r_0} = \frac{l_2^0}{r_0} = 5.06$ ;  $\frac{l_3^0}{r_0} = 0.43$ , (b)  $\frac{l_1^0}{r_0} = \frac{l_2^0}{r_0} = 4.21$ ;  $\frac{l_3^0}{r_0} = 0.95$ , (c)  $\frac{l_1^0}{r_0} = \frac{l_2^0}{r_0} = 3.58$ ;  $\frac{l_3^0}{r_0} = 1.5$ , and (d)  $\frac{l_1^0}{r_0} = \frac{l_2^0}{r_0} = 2.75$ ;  $\frac{l_3^0}{r_0} = 2.75$ . The number of elements ranges from 1896 for (a) to 2512 for (d).

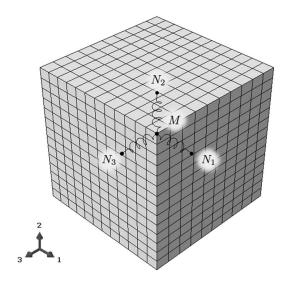


Fig. 3 The spring elements for the multiple point constraints connected to one connector node, M, in the finite element mesh

displacement in the  $x_1$  direction is then prescribed at the  $N_1$ -dummy node, while the displacements (in the  $x_2$  and  $x_3$  directions) corresponding to the desired stress triaxiality and Lode parameter are calculated and applied to the  $N_2$  and  $N_3$  dummy nodes. The displacement of the connector node, M, is coupled to the displacement of the nodes located at  $(a_1^0, x_2, x_3)$ ,  $(x_1, a_2^0, x_3)$  and  $(x_1, x_2, a_3^0)$  in the direction of the respective face normals. In this way, the displacement of the dummy nodes,  $N_i$ , is linked to the unit cell.

The displacement of the dummy nodes,  $N_i$ , is related to the forces,  $F_i$ , at the faces of the unit cell through

$$F_i = k_i (u_i^{N_i} - u_i^M)$$
 with  $i = 1, 2, 3$  (7)

and  $k_i$  being the spring element constants given by  $k_i = E(A_i/a_i^0) \times 10^{-1}$ , where the factor of  $10^{-1}$  is introduced to stabilize the numerical solution, following Ref. [34]. The forces,  $F_i$ , are the resultant of all traction across the corresponding surface and relates to the macroscopic stresses through

$$\Sigma_{11} = \frac{F_1}{A_1}, \quad A_1 = a_2^0 a_3^0$$
  

$$\Sigma_{22} = \frac{F_2}{A_2}, \quad A_2 = a_1^0 a_3^0$$
(8)  

$$\Sigma_{33} = \frac{F_3}{A_3}, \quad A_3 = a_1^0 a_2^0$$

where  $A_i$  is the area over which the forces act. Combining Eqs. (3), (7), and (8) gives the dummy node displacements

$$\rho_2 = \frac{\Sigma_{22}}{\Sigma_{11}} = \text{const.} \Rightarrow u_2^{N_2} = u_2^M + \rho_2 \frac{A_2 k_1}{A_1 k_2} (u_1^{N_1} - u_1^M)$$

$$\rho_3 = \frac{\Sigma_{33}}{\Sigma_{11}} = \text{const.} \Rightarrow u_3^{N_3} = u_3^M + \rho_3 \frac{A_3 k_1}{A_1 k_3} (u_1^{N_1} - u_1^M)$$
(9)

where  $\rho_2$  and  $\rho_3$  are input values for the stress ratio,  $u_i^{N_j}$  is the displacement of dummy node *j* in the direction of  $x_i$ ,  $u_i^M$  is the displacement in  $x_i$  direction of the connector node *M*,  $A_i$  are areas from Eq. (8), and  $k_i$  are the spring element constants. Another relevant procedure for imposing multiple point constraints without spring elements can be found in Ref. [35].

The calculations are carried out for three values of Lode parameter, L = -1, 0, and 1. The Lode parameter values L = -1 ( $\Sigma_{11} > \Sigma_{22} = \Sigma_{33}$ ) and L = 1 ( $\Sigma_{11} = \Sigma_{22} > \Sigma_{33}$ ) correspond to overall axisymmetric stress states, while L = 0 ( $\Sigma_{11} > \Sigma_{22} > \Sigma_{33}$ ) correspond

Table 2 Input parameters determining the prescribed stress state

$\frac{1+2\rho_2}{3(1-\rho_2)}$	ρ <sub>3</sub>	$\frac{1+2\rho_2}{3(1-\rho_2)}$
1	0.4	0.4
3	0.727273	0.625 0.727273
$\frac{1+\rho_2}{\sqrt{3}(1-\rho_2)}$	$\frac{1+\rho_3}{2}$	$\frac{\sqrt{3}T - 1}{\sqrt{3}T + 1}$
1	0.634	0.268
2	0.776	0.552
3	0.8386	0.6772
$\frac{2+\rho_2}{3(1-\rho_2)}$	1	$\frac{3T-2}{3T+1}$
1	1	0.25
2	1	0.57 0.70
	$ \frac{1}{2} \\ 3 \\ \frac{1 + \rho_2}{\sqrt{3}(1 - \rho_2)} \\ 1 \\ 2 \\ 3 \\ \frac{2 + \rho_2}{3(1 - \rho_2)} \\ 1 $	$ \begin{array}{cccccccccccccccccccccccccccccccccccc$

to an overall state of shear plus hydrostatic stress. For each value of Lode parameter, three triaxialities are considered, T=1, 2, and 3. The values for  $\rho_2$  and  $\rho_3$  to achieve these stress states are given in Table 2.

The calculations were carried out using the commercial finite element code ABAQUS with the gradient theory applied to the matrix material through a UEL subroutine. The reader is referred to Ref. [25] for further details on the implementation. The calculations use 20-node user-defined elements. The number of elements in the finite element meshes is varied from a minimum of 1896 to a maximum of 2512 elements, Fig. 2.

**2.3 Material Model: Strain Gradient Plasticity.** The gradient-enhanced constitutive model employed is based on the viscoplastic strain gradient plasticity theory proposed by Gudmundson [23] in the context of the mathematical formulation in terms of minimum principles proposed by Fleck and Willis [24]. For the dissipative version considered, the theory accounts for internal elastic energy storage due to elastic strain and dissipation due to the plastic strain rate,  $\dot{\epsilon}_{ijk}^{p}$ , and its spatial gradient,  $\dot{\epsilon}_{ijk}^{p}$ . Contributions from plastic strain gradients to free energy is ignored. The principle of virtual work (PVW) in Cartesian components is expressed by

$$\int_{V} \left( \sigma_{ij} \delta \dot{\varepsilon}_{ij} + (q_{ij} - s_{ij}) \delta \dot{\varepsilon}_{ij}^{p} + \tau_{ijk} \delta \dot{\varepsilon}_{ij,k}^{p} \right) \mathrm{d}V 
= \int_{S} \left( T_{i} \delta \dot{u}_{i} + t_{ij} \delta \dot{\varepsilon}_{ij}^{p} \right) \mathrm{d}S$$
(10)

where  $\sigma_{ij}$  and  $s_{ij} = \sigma_{ij} - 1/3\delta_{ij}\sigma_{kk}$  are the Cauchy stress tensor and the stress deviator, respectively. The micro-stress,  $q_{ij}$ , is work conjugate to the plastic strain rate,  $\dot{\varepsilon}_{ij}^{p}$ , and  $\tau_{ijk}$  is a higher order stress, work conjugate to the plastic strain rate gradient,  $\dot{\varepsilon}_{ij,k}^{p}$ . The right-hand side of the PVW includes the conventional traction,  $T_i = \sigma_{ij}n_j$  work conjugate to the boundary displacement rate,  $\dot{u}_i$ , and the higher order traction,  $t_{ij} = \tau_{ijk}n_k$ , work conjugate to the plastic strain rate,  $\dot{\varepsilon}_{ij}^{p}$ . Here, the outward unit normal to the surface *S* is  $n_i$ . Balance laws for the stress quantities are given by

$$\sigma_{ij,j} = 0 \quad \text{and} \quad q_{ij} - s_{ij} - \tau_{ijk,k} = 0 \tag{11}$$

where the first set of equations is the conventional equilibrium equations in the absence of body forces, and the second set is the higher order equilibrium equations. The higher order boundary conditions are imposed such that the void surface is higher order traction free, while symmetry conditions are imposed at the exterior of the cell through  $\varepsilon_{12} = 0$ .

**2.4 Constitutive Equations.** The rate-dependent viscoplastic formulation employs a potential to account for plastic dissipation as follows:

$$\Phi[\dot{E}^{p}, E^{p}] = \int_{0}^{\dot{E}^{p}} \sigma_{c} \left[\dot{E}^{p'}, E^{p}\right] \mathrm{d}\dot{E}^{p'}$$
(12)

where  $\sigma_c$  is the gradient-enhanced effective stress, related to the current matrix flow stress through  $\sigma_c = \sigma_F [E^p] (\dot{E}^p / \dot{\epsilon}_0)^m$ , with  $\dot{\epsilon}_0$  denoting the reference strain rate and *m* denoting the rate sensitivity exponent. The material in this study does not undergo strain hardening, making  $\sigma_F$  independent of  $\dot{E}^p$  and equal to the material yield stress  $\Sigma_0$ . The viscoplastic law is implemented following the algorithm presented in Ref. [36] to efficiently approach the rate-independent limit. A gradient-enhanced effective plastic strain rate is given by

$$(\dot{E}^{p})^{2} = \frac{2}{3} \dot{\varepsilon}_{ij}^{p} \dot{\varepsilon}_{ij}^{p} + L_{D}^{2} \dot{\varepsilon}_{ij,k}^{p} \dot{\varepsilon}_{ij,k}^{p}$$
(13)

and the associated work conjugate gradient-enhanced effective stress by

$$\sigma_c^2 = \frac{3}{2} q_{ij} q_{ij} + \frac{1}{L_D^2} \tau_{ijk} \tau_{ijk}$$
(14)

where  $L_D$  is a dissipative constitutive length parameter that enters for dimensional consistency. The superscript *D* refers to dissipative quantities, and the dissipative stress quantities are given by

$$q_{ij}^{D} = \frac{2}{3}\sigma_{c}\frac{\dot{\varepsilon}_{ij}^{p}}{\dot{E}^{p}}, \quad \tau_{ijk}^{D} = L_{D}^{2}\sigma_{c}\frac{\dot{\varepsilon}_{ij,k}^{p}}{\dot{E}^{p}}$$
(15)

The dissipative length parameter controls the strengthening size effect with an increase in the dissipative length parameter giving an increase in the apparent yield stress in the presence of strain gradients, see Refs. [37,38]. This work is a limit load analysis, which, by definition, is done to determine the overall yield criterion for a given, specific configuration. Limit load analyses normally idealize materials as perfectly plastic. To avoid strain hardening from the energetic gradient contributions, the energetic length parameter,  $L_E$ , has been set to zero in this work, and, consequently, the corresponding energetic quantities are omitted.

#### **3** Numerical Results and Discussion

Throughout, the following material parameters are used:  $\Sigma_0/E = 0.001$ ,  $\nu = 0.3$ , and m = 0.01, where  $\Sigma_0$  is the yield stress, *E* is Young's modulus,  $\nu$  is the Poisson ratio, and *m* is the strain rate sensitivity exponent. The value of *m* is considered sufficiently small for the results to approximate a rate-independent material response. The influence of the Lode parameter, *L*, the stress triaxiality, *T*, and the normalized length parameter,  $L_D/r_0$ , is studied. The effect of the inter-void ligament size is discussed in combination with the other parameters, *L*, *T*, and  $L_D/r_0$ .

**3.1** Critical Equivalent Stress at Localization. Figure 4 presents the equivalent stress–strain curves for two distinct Lode parameters, L = -1 and 1, but for a fixed stress triaxiality, T = 3, and a fixed inter-void ligament size of  $l_3/r_0 = 1.5$ . The equivalent stress–strain curves are depicted for three length parameters, being,  $L_D/r_0 = 0.2$ , 0.5, and 1 as well as for the conventional limit, where  $L_D/r_0 = 0$ .

The material response shows a clear effect of plastic strain gradients, such that the larger the length parameter, the higher the equivalent stress level. This means that an increase in the stress level is obtained when downscaling the microstructure and, thus, yielding

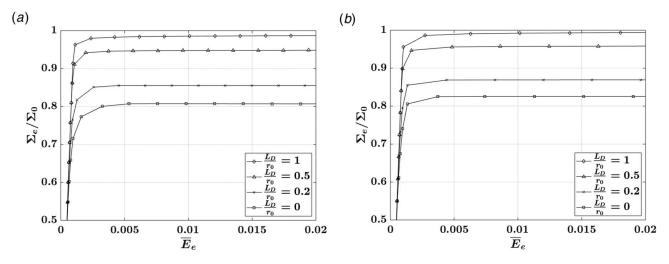


Fig. 4 Equivalent stress–strain curve for an inter-void ligament size of  $l_3/r_0 = 1.5$  under loading conditions giving Lode parameters of (a) L = -1 and (b) L = 1 and a triaxiality of T = 3

of the material is delayed due to the increasing strain gradient strengthening. The critical equivalent stress,  $\Sigma_e^c / \Sigma_0$ , signaling localization (and coalescence) is taken to be at the plateau of the equivalent stress-strain curve. Several ways exists to establish a coalescence criteria based on either critical stress or strain. The method employed in this study is inspired by the work of Ref. [39]. The critical stresses have been extracted from the end of the equivalent stress-strain curves (as shown in Figs. 4(*a*) and 4(*b*)). Taking the example of Fig. 4(*a*), the conventional material ( $L_D/r_0 = 0$ ), the difference between the equivalent stress at  $E_e = 0.02$  and 0.01 is less than 0.04%.

**3.2 Conventional Material: Effect of the Inter-Void Ligament Size.** The conventional limit,  $L_D/r_0 = 0$ , is considered to set the scene for the study of material size effects. The focus here is the effect of inter-void ligament size on the critical stress at localization under various loading conditions.

First, three values of the Lode parameter are considered, L = -1, 0, and 1, for a fixed stress triaxiality, T = 2. Figure 5 shows the critical equivalent stress as a function of the inter-void ligament size. For the six smallest inter-void ligaments, the critical equivalent stress is seen to increase when the inter-void ligament becomes bigger irrespective of the value of the Lode parameter. The increase in the critical stress ties to localization occurring more easily in

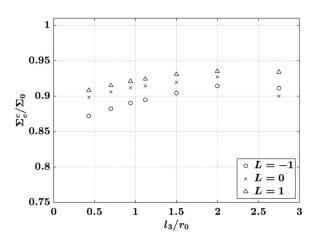


Fig. 5 Critical equivalent stress versus normalized inter-void ligament size for three values of the Lode parameter with T = 2 and  $L_D/r_0 = 0$ 

small inter-void ligaments lowering the load-carrying capacity of the unit cell. As the inter-void ligament size increases, the  $l_3$  ligament can sustain a higher stress level before localization, leading to an increase in critical equivalent stress. Also, for the six smallest inter-void ligaments, an increase in the critical stress is found with the increasing Lode parameter values. Thus, the lowest critical equivalent stress is found for L = -1. The dependence on the Lode parameter can be rationalized by considering the imposed stress state. In comparison to the other cases, the relative stress component,  $\rho_3$ , is the largest when L = -1 (see Table 2), and localization is therefore expected in the  $l_3$  ligament at a lower overall deformation. In contrast, the  $\rho_3$  takes the lowest value for L = 1, resulting in delayed localization and the highest critical equivalent stress obtained. In Ref. [5], void coalescence was found to occur along the ligament with the smallest applied stress for L > -1. For all Lode parameters, the relative stress component in the  $l_3$  ligament will be smallest as  $\rho_3$  is always the lowest stress ratio. For L=-1, coalescence occurs in the direction of the smallest inter-void ligament size. This corresponds to the  $l_3$  ligament for all geometries except when  $l_3/r_0 = 2.75$  as this is a perfect cube, Table 1.

There is, however, a shift in the localization pattern when the  $l_3$ ligament becomes sufficiently wide, for example, a drop in the coalescence stress is found for  $l_3/r_0 = 2.75$  for L = 0. The load-carrying capacity of the material increases when the distribution of voids diverge from a regular array, i.e., when  $l_3/r_0 \neq 2.75$ . However, the load-carrying capacity will decrease if the arrangement of the voids is such that the inter-void ligament size, in any direction, is too small (e.g.,  $l_3/r_0 < 2$ ). At the configuration with  $l_3/r_0 = 2.75$ , there is no bias toward the  $l_3$  ligament since the unit cell takes a cubic shape. The shift in the localization is especially prominent for L=0 (a state of combined hydrostatic tension and shear) where plastic flow localizes at  $\approx$ 45 deg across the cubic unit cell, leading to an early loss of load-carrying capacity. The shift in the localization is demonstrated by depicting the contours of the effective plastic strain for two distinct unit cells  $(l_3/r_0 = 1.5 \text{ and } 2.75)$ subjected to L = 0 and T = 2 in Figs. 6 and 7. The material response remains conventional such that  $L_D/r_0 = 0$ , and the loading conditions are described by L=0 and T=2. For the conventional material, the second term of Eq. (13) is zero  $(L_D=0)$  and the term gradient-enhanced effective plastic strain refers to the time integration of only the first term of Eq. (13). For the elongated unit cell  $(l_3/r_0 = 1.5)$ , localization is seen to occur in the smallest ligament,  $l_3$ , whereas localization is seen to occur along two corners of the cubic unit cell  $(l_3/r_0 = 2.75)$ , indicating that the deformation is localized along  $\approx$ 45 deg, i.e., across the diagonal. Figure 6 shows the contour of equivalent plastic strain across the faces of the cell, while Figs. 7(a) and 7(b) show the contour of the effective plastic

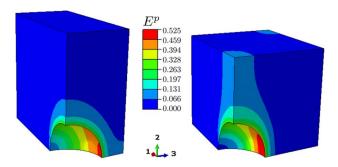


Fig. 6 Distribution of effective plastic strain for L = 0, T = 2, and  $L_D/r_0 = 0$ , for  $I_3/r_0 = 1.5$  to the left and  $I_3/r_0 = 2.75$  to the right at a macroscopic effective strain of  $\overline{E}_e = 0.03$ . For  $I_3/r_0 = 1.5$ , localization is favored in the smallest ligament,  $I_3$ . For the cubic unit cell, however, there is no bias toward any of the ligaments and deformation localizes along  $\approx$ 45 deg, i.e., across the diagonal.

strain in the diagonal cross section of both unit cells at an overall effective strain of  $\overline{E}_e = 0.03$ . By comparing the two contours, it is seen that plastic flow is observed across the entire cross section, indicating localization at  $\approx$ 45 deg for the cubic model,  $l_3/r_0 =$  2.75. In contrast, the plastic flow is constricted for  $l_3/r_0 =$  1.5 shown top right in Fig. 7.

Next, the effect of stress triaxiality is considered. In Fig. 8, the critical stress for a conventional material,  $L_D/r_0 = 0$ , is shown as a function of the inter-void ligament size for T=1, 2, and 3 for a fixed value of the Lode parameter, L = -1. In the conventional limit, a high level of stress triaxiality yields low critical stress for all ligament sizes considered. The reason being that a high stress triaxiality corresponds to higher relative stress components,  $\rho_2$ and  $\rho_3$ . Figure 8 shows little effect of ligament size on the critical equivalent stress for the low value of triaxiality. For T = 1, the relative stress transverse to the main loading direction is insufficient to invoke localization in the inter-void ligament and the effect of the ligament size will be limited. The cell instead undergoes macroscopic localization and, consequently, does not exhibit a profound dependence on the inter-void ligament size. This is in line with results presented in Ref. [1], where T=1 has been found to be the limit below which the onset of macroscopic localization is

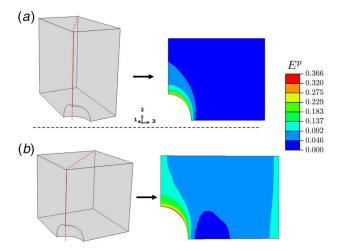


Fig. 7 Distribution of effective plastic strain along a cut from corner to corner for L = 0, T = 2, and  $L_D/r_0 = 0$  at  $E_e = 0.03$  for two geometries: (a)  $I_3/r_0 = 1.5$  and (b)  $I_3/r_0 = 2.75$ . (a) Shows that plasticity has not localized along 45 deg and for this geometry localization is favored in the smaller ligament, while (b) shows that a band, indicated by the dotted line, has formed at a 45 deg angle to the main loading axis (the  $x_1$  axis), thus lowering the critical effective stress.

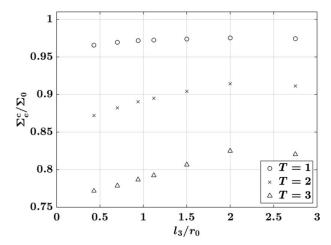


Fig. 8 Critical equivalent stress versus normalized inter-void ligament size for three values of the stress triaxialities with L = -1 and  $L_D/r_0 = 0$ 

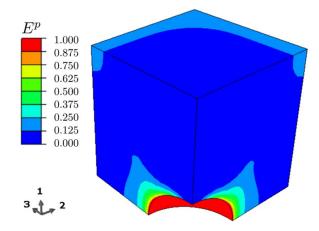


Fig. 9 Bands of plastic flow in the cubic unit cell  $(l_3/r_0 = 2.75)$ and  $L_D/r_0 = 0$  at an overall equivalent strain of  $\overline{E}_e = 0.08$ . The loading conditions applied to give an axisymmetric stress state with L = -1 and T = 2. Note the rotated coordinate system to show the symmetry of the plastic flow given by the cubic unit cell and  $\rho_2 = \rho_3$  for L = -1.

essentially simultaneous with void coalescence. The results for T=2 and T=3 in Fig. 8 show that the critical equivalent stress is dependent on inter-void ligament size.

A small drop in the critical equivalent stress is seen to occur for the largest ligament for all values of triaxiality in Fig. 8 The effect is most prominent for the highest triaxiality, T = 3. Figure 9 shows the contour gradient-enhanced effective plastic strain of the cubic cell  $(l_3/r_0 = 2.75)$  at an effective stress of  $\overline{E}_e = 0.08$ . At a sufficiently large strain, plasticity is seen to initiate at the corner opposite to the void. Due to the symmetry of both the loading condition  $(\Sigma_2 = \Sigma_3 \text{ for } L = -1)$  and the unit cell, bands of plastic deformation are observed to stretch across the  $x_1 - x_2$  and  $x_1 - x_3$  faces, ultimately lowering the coalescence stress giving the drop as shown in Fig. 8.

The effect of gradient strengthening in the matrix material is introduced through the length parameter  $L_D$  (see Sec. 2.3). One can imagine downscaling the microstructure when increasing the value of  $L_D/r_0$ . Three values of the length parameter,  $L_D/r_0 = 0.2$ , 0.5, and 1, are considered in the following for all combinations of the Lode parameter, L = -1, 0, 1, and stress triaxiality, T = 1, 2, 3. Figure 10 shows the critical effective stress,  $\Sigma_e^c / \Sigma_0$ , as a function of the inter-void ligament size,  $l_3/r_0$ , for all combinations. The

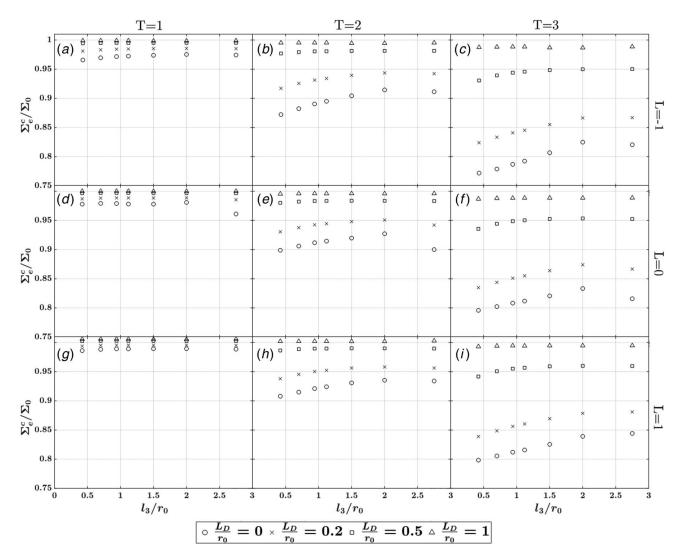


Fig. 10 The critical equivalent stress as a function of the smallest inter-void ligament size. Three values of the Lode parameter are considered, L = -1, 0, and 1. For each Lode parameter, three values of the stress triaxiality are considered, T = 1, 2, and 3. Throughout, the parameters  $\Sigma_0/E = 0.001$ , v = 0.3, and m = 0.01 are used. The initial void volume fraction is  $f_0 = 0.01$ . The length parameter that enters through the gradient plasticity theory is  $L_D/r_0 = 0.2$ , 0.5, and 1. A conventional material is modeled with  $L_D/r_0 = 0$  and used as a reference.

results obtained for a conventional material,  $L_D/r_0 = 0$ , are presented as a reference (see Sec. 3.2).

The general observation is that the critical stress at localization increases with the magnitude of the length parameter (downscaling the microstructure). However, the critical stress has a natural upper bound where the gradient strengthening is so severe that the entire matrix material yields. At such large values of the length parameter, the effect of the Lode parameter, stress triaxiality, and inter-void ligament size vanish and the critical equivalent stress is identical for all combinations of geometry and loading condition. The threshold value is evident from Figs. 10(a)-10(i).

Figures 11(a)-11(c) show how the length parameter affects the plastic flow in the unit cells by comparing contours of the gradient-enhanced plastic equivalent strain,  $E^p$  (see Eq. (13)) for a ligament size of  $l_3/r_0 = 1.5$  subject to L = -1 and T = 3. The contours are extracted at an overall equivalent strain of  $\overline{E}_e = 0.02$ . Figure 11(a) displays the conventional material response where localization occurs in the  $l_3$  ligament. At the same level of the overall deformation, a significantly lower effective plastic strain is observed in Figs. 11(b) and 11(c) when increasing the length parameter. For  $L_D/r_0 = 0.2$ , Fig. 11(b), some plasticity is seen to develop in the  $l_3$  ligament, but far less than in the conventional case, while

the plasticity has barely initiated at this level of the deformation for  $L_D/r_0 = 0.5$ , Fig. 11(*c*). The corresponding equivalent stress is shown in Figs. 11(*d*)–11(*f*). It is seen that the level of stress in the unit cell increases with the increasing length parameter. The critical equivalent stress is seen to increase with the increased length parameter in Fig. 10, and the material can therefore withstand higher stresses.

Figure 12 shows the change in the deformation mechanism that occurs with the increased gradient strengthening. The contour of the normalized rate of equivalent plastic strain,  $E^P/\overline{E}_e$ , is shown for the unit cell with the smallest inter-void ligament,  $l_3/r_0 = 0.43$  under loading conditions giving L=1 and T=3 for the conventional material with  $L_D/r_0 = 0$  and the material with the greatest gradient strengthening contribution,  $L_D/r_0 = 1$ . Figure 12(*a*) shows that plastic deformation has developed and localized in the  $l_3$  ligament, as expected for a conventional material at this loading condition. For the matrix surrounding the  $l_3$  ligament, plasticity is reduced in favor of localization in the  $l_3$  ligament. However, for the gradient strengthened material, plasticity is not only less developed, in line with the gradient strengthening, but also smeared out across the unit cell, see Fig. 12(*b*). Localization is to a little extent observed in the  $l_3$  ligament, but overall the entire cell experiences plasticity.

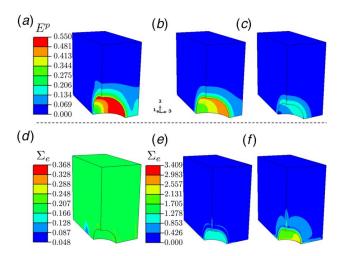


Fig. 11 Distribution of gradient-enhanced effective plastic strain for L = -1, T = 3, and  $l_3/r_0 = 1.5$  for (a) the conventional material,  $L_D/r_0 = 0$ , (b)  $L_D/r_0 = 0.2$ , and (c)  $L_D/r_0 = 0.5$  at a macroscopic effective strain of  $\overline{E}_e = 0.02$ . The effective stress,  $\Sigma_e$ , for the same configuration is shown in the cells at the bottom, also here with (d) the conventional material, (e)  $L_D/r_0 = 0.2$ , and (f)  $L_D/r_0 = 0.5$ .

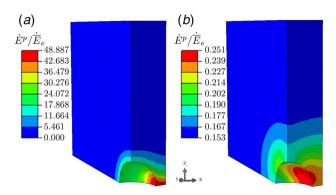


Fig. 12 Change in deformation mode with the increased length parameter for  $I_3/r_0 = 0.43$  with loading conditions described by L = 1 and T = 3. The conventional material with  $L_D/r_0 = 0$  is shown in (a), while (b) shows a gradient enriched material with  $L_D/r_0 = 1$ .

This is indicative of a change in deformation mechanism along the lines of the one observed in Ref. [1] for a stress triaxiality of 1. However, here it is seen with an increasing length parameter. As  $L_D/r_0$  increases, the cell is more likely to undergo simultaneous macroscopic localization and void coalescence in contrast to a conventional material where the cell predominantly undergoes void coalescence for the same loading conditions.

The combined effect of the stress triaxiality (for a fixed Lode parameter) and the length parameter is visualized by the rows in Fig. 10, while the combined effect of the Lode parameter (for a fixed stress triaxiality) and length parameter is visualized by the columns in Fig. 10. Qualitatively, for a fixed stress triaxiality value, the length parameter has a nearly identical impact for all values of the Lode parameter. It is, however, interesting that the drop in coalescence stress the cubic unit cell  $(l_3/r_0 = 2.75)$  subject to L=0 diminishes with the increasing length parameter for all values of stress triaxiality, Figs. 10(d)-10(f). This is because increased gradient strengthening delays the intensification of the plastic flow and homogenizes the plastic strain field.

For the lowest stress triaxiality value, T=1, the effect of the length parameter is small. Nonetheless, the plastic strain gradients that build up around the void give rise to the small increase in

gradient strengthening. For the loading conditions giving T=1, the onset of localization is significantly delayed, thus allowing the material to withstand higher critical stress with a smaller dependence on the inter-void ligament size. The deformation mechanism prevailing at this low value of triaxiality, where macroscopic localization and void coalescence occur simultaneously [1], implies that the gradients surrounding the void will not influence the critical equivalent stress to a great extent, as the deformation takes place in the entire unit cell.

For a higher value of stress triaxiality, T=2, the effect of the length parameter is more prominent as shown in Fig. 10, and the smaller the inter-void ligament size, the greater the effect of the length parameter is. This is because, at higher stress triaxiality values, the plastic flow tends to localize in the inter-void ligaments as the ligaments diminish in size. The localization induces large plastic strain gradients that in turn contribute to strengthening. The gradient-induced strengthening in the inter-void ligament then inhibits further plastic flow localization and delays void coalescence. Although not shown here, for L = -1 and T = 2, the gradient strengthening is sufficiently large that increasing the value of  $L_D/r_0$ from 1 to 2 has a negligible effect. For the intermediate length parameter,  $L_D/r_0 = 0.5$ , the effects of triaxiality and inter-void ligament size are still visible but greatly reduced due to the smaller degree of gradient strengthening. For the smallest value of the length parameter,  $L_D/r_0 = 0.2$ , the critical equivalent stress values follow those of the conventional material, just at a higher relative level for all inter-void ligament size considered. For L=0 and L=1, for T=2, the same effect is seen. The most pronounced effect of the length parameter is seen for L=-1, T=3, and  $l_3/2$  $r_0 = 0.43$  as this configuration has the lowest critical effective stress for the conventional material, but shows the same critical stress for  $L_D/r_0 = 1$  as in the remaining results.

#### 4 Summary and Conclusions

The interaction of the inter-void ligament size and the gradient-induced material size effect on void coalescence is investigated for a range of imposed stress states, here characterized by fixed values of the stress triaxiality and the Lode parameter. To this end, three-dimensional finite element unit cell calculations for a single initially spherical void embedded in strain gradient-enhanced material matrix are carried out. A conventional material matrix (absence of gradient induced strengthening effects) is considered as reference. Increasing the length parameter, and thereby the gradient effect, is equivalent to downscaling the microstructure. All microstructures considered in this work contain voids that are below a critical flaw size [40]. Thus, plasticity theory will reign the material response as the voids are considered too small to be treated as cracks.

The results for the conventional material show that the critical coalescence stress increases when increasing the inter-void ligament size. The effect of the inter-void ligament size is, however, dependent on the imposed stress triaxiality, such that the effect of the inter-void ligament size increases with the increasing stress triaxiality. However, above a certain threshold for the inter-void ligament size, the results show a slight decrease in the critical stress. This drop has to do with a transition from plastic flow localization within the smallest inter-void ligament to plastic flow localization at  $\approx$ 45 deg to the main loading axis. The transition in the plastic flow localization at Lode parameter of L=0. However, irrespective of the Lode parameter value, the transition occurs as the unit cells approach a cubic geometry.

For a void embedded in a strain gradient-enhanced material matrix, the value of the critical coalescence stress increases with the increasing length parameter, i.e., increasing the gradient strengthening effect. The effect of the length parameter is found to intensify with the increasing imposed stress triaxiality and the decreasing inter-void ligament size. This is due to a propensity

for plastic flow localization in the inter-void ligament when the ligament is small and the stress triaxiality high. Plastic flow localization introduces large plastic strain gradients, which in turn strengthens the ligament and delays further localization of the plastic flow. The strengthening from plastic strain gradients also leads to a weakened dependency in the critical coalescence stress on the inter-void ligament size. Finally, the results show that there exists a natural upper bound where the gradient strengthening is so severe that the entire matrix material yields. For very large values of the length parameter, the effect of the imposed stress state and the inter-void ligament size vanish, and the critical equivalent stress is identical for all combinations of the unit cell geometry and the loading conditions considered.

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#### **Conflict of Interest**

There are no conflicts of interest.

#### **Data Availability Statement**

The datasets generated and supporting the findings of this article are obtainable from the corresponding author upon reasonable request. The authors attest that all data for this study are included in the paper. Data provided by a third party listed in Acknowledgment.

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