

ENERGY & POWER BALANCE

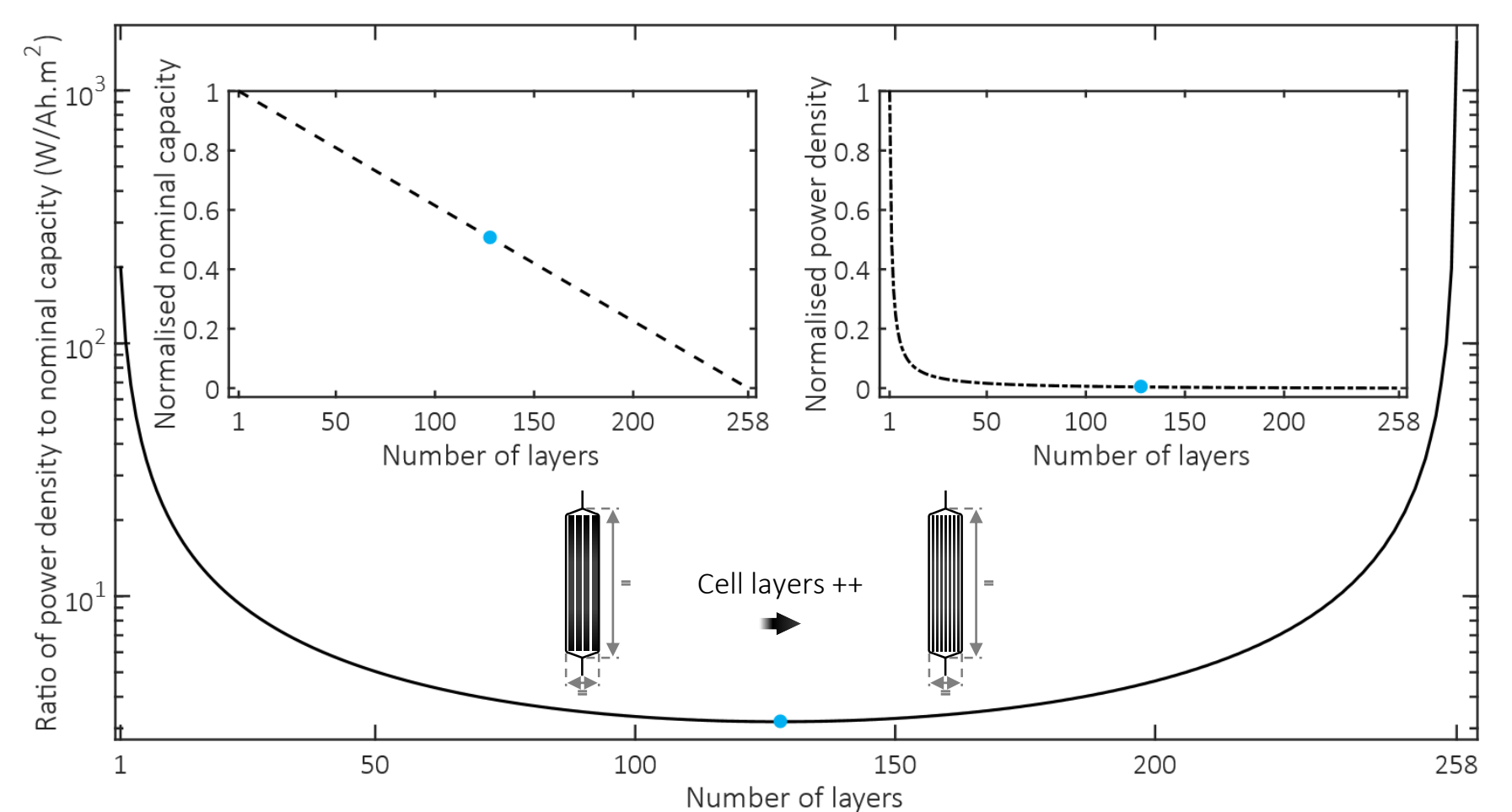
- Conflicting requirements pose a layer optimisation problem
- Desire trading of energy & power in equally-dimensioned cells
- Layer reconfiguration trades fraction of active material mass with surface area available for redox reaction
- Empirical determination of optimal layer count is slow, costly & may not provide energy-density maximising result
- We propose a rapid & inexpensive model-based alternative

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LAYER OPTIMISATION

- The optimal (i.e. range-maximising) layer configuration is the minimum number of layers that meets EV acceleration and fast charging targets
- Initially, we gain a lot of rate capability for little energy density loss since power density per layer decreases faster than cell nominal capacity
- At higher layer counts it becomes increasingly expensive, in terms of energy density sacrificed, to accommodate higher powers
- **Efficient designs employ < half the maximum possible number of layers**

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1 Define vehicle

xEV platform	PHEV
Powertrain	🔌 (series)
Module & cell configuration	8S1P (mod.) 12S1P (cells)
xEV mass (w/o cells)	1,654 kg (inc. ICE)
Fast charge SOC range	30 - 80 %

2 Define criteria

<i>Fast charging</i>	<i>Acceleration</i>
$T(t) < T_{max}$	$T(t_f) < T_{max}$
$V(t) < V_{max}$	$V(t_f) > V_{min}$
$z(t) \geq z^*$	$z(t_f) > z_{min}$
$C_s^*(t) < C_{s,sat}$	
$t < t_{max}$	

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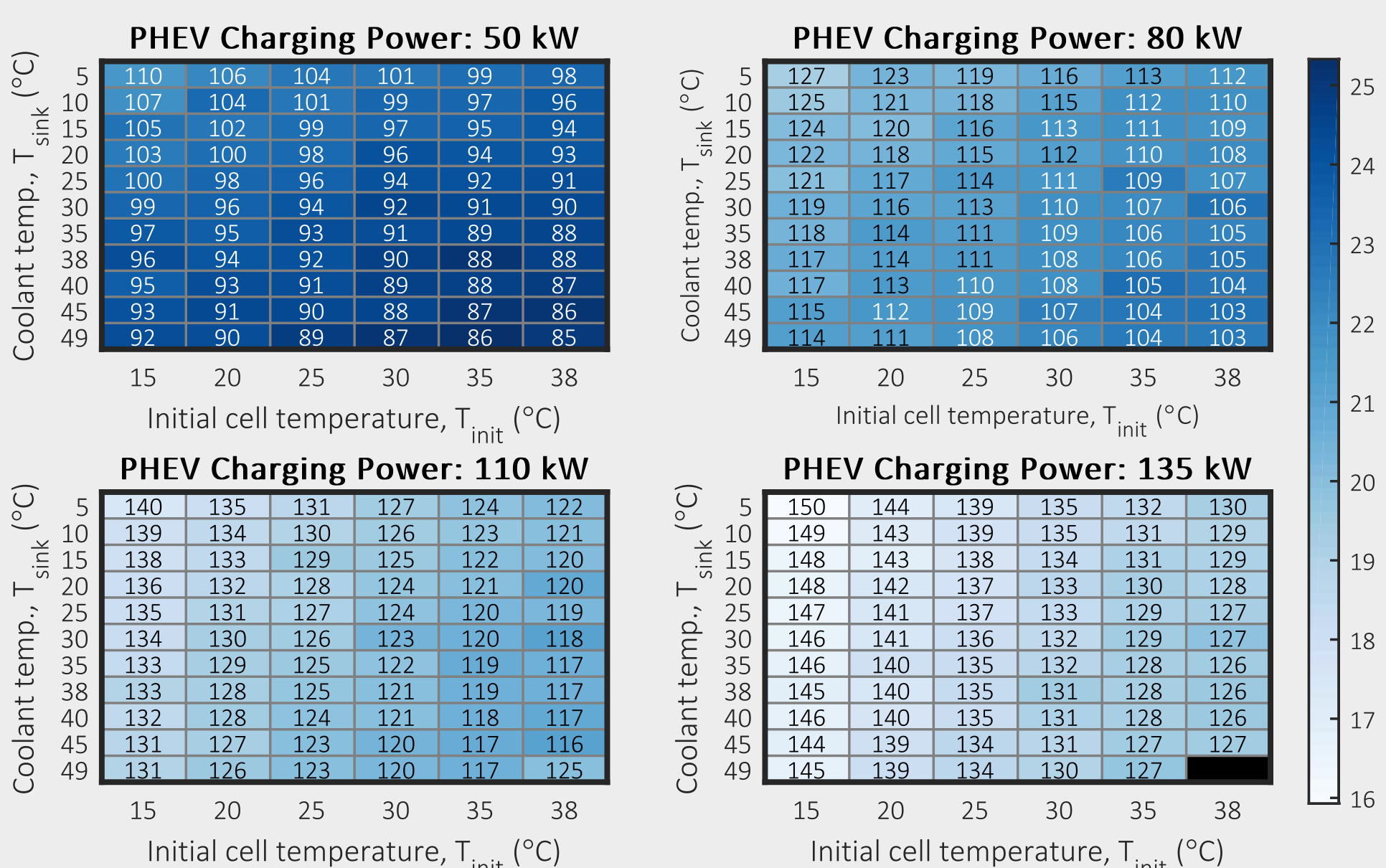
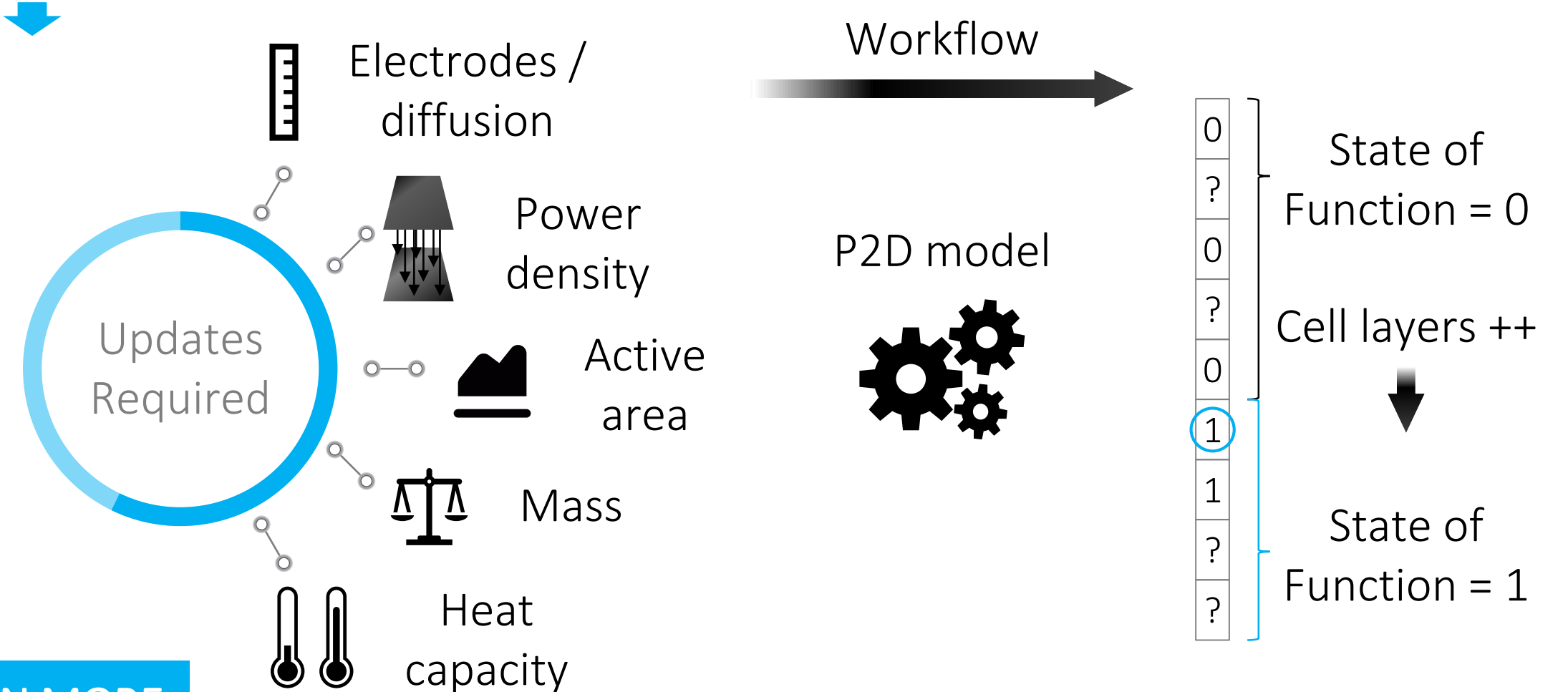
Li-PLATING PROTECTED FAST CHARGE

- Specify desired xEV configuration & define performance criteria
- Cells undergo simulated vehicle acceleration & fast charging
- Charge time is minimised with a constant power strategy
- **Design for highest powers & impose an Li concentration limit**
- **Cell designs exhibit Li-plating protection & max. energy density**

P2D SIMULATION

- Custom binary search & open-source electrochemical P2D model capable of directly accepting *power* inputs
- Efficiently screen layer configurations, identifying optimal value
- Each new layer configuration requires updated electrode thicknesses, active surface area, cell mass and heat capacity
- Vector of layer State-of-Functions is produced; lowest layer count with a unity SoF is the optimal

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TAILORED CELL DESIGN MAPS

- Repeat for new ambient & cell temperatures to generate cell design maps precisely tailored to vehicle fast charge targets
- Values in coloured cells are optimal layer configurations
- Map colour is usable capacity; charge added, 30 – 80 % SOC window
- Black colours indicate unsuitable cell materials & thermal management system for specified temperatures & design targets
- Faster & lower cost than iterative, empirical development
- **Method can offer xEV range extension over empirical cell design**
- **Enables common module design for xEV platforms, lowering R&D costs & time to market for automotive OEMs**