Imperial College London

Optimising Li-ion Cell Layers Rapid Cell Design For EV Fast Charging

Ian D. Campbell*, Krishnakumar Gopalakrishnan, Dr. Monica Marinescu, Dr. Marcello Torchio, Dr. Gregory J. Offer, Prof. Davide Raimondo

i.campbell15@imperial.ac.uk @lan_Campbell1 & @Imperial_ESE *PhD Candidate



• The optimal (i.e. range-maximising) layer configuration is the minimum number of layers that meets EV acceleration and fast charging targets Initially, we gain a lot of rate capability for little energy density loss since 0 power density per layer decreases faster than cell nominal capacity • At higher layer counts it becomes increasingly expensive, in terms of energy density sacrificed, to accommodate higher powers Efficient designs employ < half the maximum possible number of layers 0

ENERGY & POWER BALANCE

- Conflicting requirements pose a layer optimisation problem
- Desire trading of energy & power in equally-dimensioned cells 0
- Layer reconfiguration trades fraction of active material mass with 0 surface area available for redox reaction
- Empirical determination of optimal layer count is slow, costly & may not provide energy-density maximising result
- We propose a rapid & inexpensive model-based alternative



1 — Define	vehicle	2 <u>Define</u>	<u>criteria</u>
xEV platform	PHEV	Fast charging	Acceleration
Powertrain	🕼 — 🗐 (series)	$T(t) < T_{max}$	$T(t_f) < T_{max}$
Module & cell configuration	8S1P (mod.) 12S1P (cells)	$V(t) < V_{max}$	$V(t_f) > V_{min}$
xEV mass (w/o cells)	1,654 kg (inc. ICE)	$z(t) \ge z^*$ $C^*(t) \le C_*$	$z(t_f) > z_{min}$
Fast charge SOC range	30 - 80 %	$t < t_{max}$	LEARN

LI-PLATING PROTECTED FAST CHARGE

- Specify desired xEV configuration & define performance criteria • Cells undergo simulated vehicle acceleration & fast charging Charge time is minimised with a constant power strategy Design for highest powers & impose an Li concentration limit
- Cell designs exhibit Li-plating protection & max. energy density 0

P2D SIMULATION

- Custom binary search & open-source electrochemical P2D model capable of directly accepting *power* inputs
- Efficiently screen layer configurations, identifying optimal value 0
- Each new layer configuration requires updated electrode 0 thicknesses, active surface area, cell mass and heat capacity Vector of layer State-of-Functions is produced; lowest layer count 0 with a unity SoF is the optimal



Heat capacity

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Function = 1?

	PHE	V Cha	rging	Powe	er: 50	kW		PHE\	/
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25	121	117	114	111	109	107		24	
30	119	116	113	110	107	106			
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5 10 15 20 25	150 149 148 148 147	144 143 143 142 141	139 139 138 137 137	135 135 134 133 133	132 131 131 130 129	130 129 129 128 127		19	Charge p
5 10 15 20 25 30	150 149 148 148 147 146	144 143 143 142 141 141	139 139 138 137 137 137 136	135 135 134 133 133 132	132 131 131 130 129 129	130 129 129 128 127 127		19 18	Charge p
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TAILORED CELL DESIGN MAPS

- Repeat for new ambient & cell temperatures to generate cell 0 design maps precisely tailored to vehicle fast charge targets
- Values in coloured cells are optimal layer configurations
- Map colour is usable capacity; charge added, 30 80 % SOC window
- Black colours indicate unsuitable cell materials & thermal 0 management system for specified temperatures & design targets
- Faster & lower cost than iterative, empirical development 0
- Method can offer xEV range extension over empirical cell design
- Enables common module design for xEV platforms, lowering R&D 0 costs & time to market for automotive OEMs